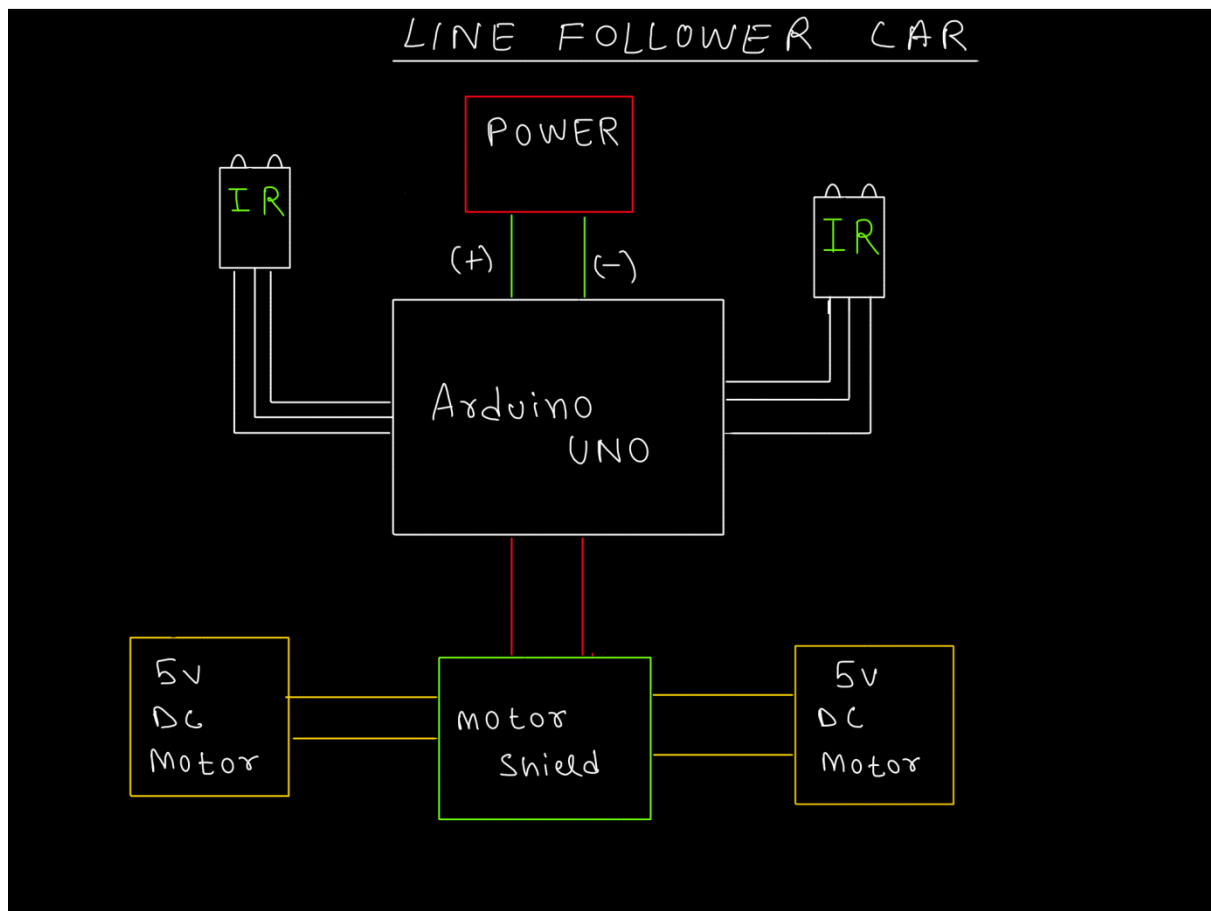# LINE FOLLOWER CAR

Description: The Integrated ATL project Line Follower Car was ideated to make an autonomous vehicle which can drive itself by detecting a line bar and can prove itself helpful in those conditions were humans fail to reach.

Materials Required:

1. Arduino Uno (Micro-controller)
2. 2 x Infrared Sensor (Line Detector)
3. Adafruit Motor Shield (Motor Driver)
4. Jumper Wires
5. 5v Dc Motors
6. Battery (As power Source)

Images Of The Model :

Achievements:

Team: